SSOP8-P-0.50A

Weight: 0.01 g (typ.)

TOSHIBA CMOS Digital Integrated Circuits Silicon Monolithic

TC9WMA2FK

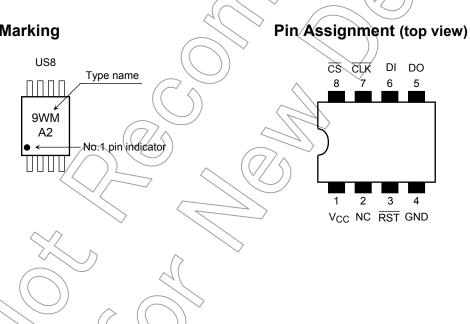
2,048-Bit (256 × 8 Bit) Serial E²PROM

The TC9WMA2FK is electrically erasable/programmable nonvolatile memory (E²PROM).

Features

- Serial data input/output
- Programmable in units of one word and collectively erasable in one operation
- Automatically set programming time (built-in timer)
- Programming time: 10 ms (max) (V_{CC} = 3.0 to 5.5 V)
- $12 \text{ ms} (\text{max}) (\text{V}_{\text{CC}} = 2.3 \text{ to } 2.7 \text{ V})$
- Overwrite enabled or disabled by software
- Single power supply and low power consumption
- Operating voltage range for reading: $V_{CC} = 1.8$ to 5.5 V
- Operating voltage range for writing: $V_{CC} = 2.3$ to 5.5 V
- Wide operating temperature range (-40 to 85°C)

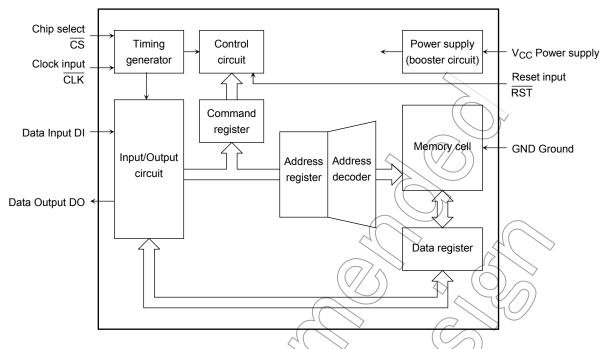
Product Marking



2007-10-19

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Block Diagram



Pin Function

i i unction		
Pin Name	Input/Output	Function
CS	Input	Chip select \overline{CS} selects the chip. Always return \overline{CS} high temporarily before executing instructions.
CLK	Input	Clock input The data on DI is latched by a rising edge of $\overline{\text{CLK}}$. Data is output to DO by a falling edge of $\overline{\text{CLK}}$. $\overline{\text{CLK}}$ is effective when $\overline{\text{CS}}$ is low.
DI	Input	Serial data input This pin is used to enter addresses, commands, and data into the chip.
DO	Output	Serial data output This pin outputs data from the chip.
RST	Input	Reset input A low on this input resets the chip.
NC		No connection (not connected internally)
Vcc	Power supply	1.8 V~5.5 V (for reading) 2′3~5.5 V (for writing)
GND		0 V (GND)
GND		

Functional Description

1. Types of Instructions

Onenation	A datas s s	Command								Dete	
Operation	Address	C0	C0 C1 C2 C3					Data			
Read	A0~A7	1	0	0	0	0	0	0	0		
Program	A0~A7	0	1	1	0	0	0	0	0	D0~D7	
All erase	******	0	0	1	1	0	0	0	0		
Busy monitor	******	1	0	1	1	0	0	0	0	(())	
Overwrite enable	******	1	0	0	1	0	0	0	0		
Overwrite disable	******	1	1	0	1	0	0	0	(0)	$(\) $	
Read Auto-incremented	A0~A7	1	0	0	0	1	0	Ø	0	\bigcirc	

*: Don't care

2. Operation Method

Be sure to drive \overline{CS} and \overline{CLK} high temporarily before entering an instruction After \overline{CS} is asserted low, \overline{CLK} becomes effective, acting as a serial transfer synchronizing signal. The data on DI is latched on a rising edge of \overline{CLK} , while data is output to DO on a falling edge of \overline{CLK}

Instructions can only be executed when the chip is not being programmed or collectively erased (i.e., when the ready/busy status signal is high). However, the Monitor Busy instruction can be entered at any time.

- Only the commands listed in the above table can be used. Do not use any other command.
- Read

Entering the Read instruction causes memory data at the specified address to be read out and serially output from the DO pin.

• Program

Entering the Program instruction causes overwrite operation to automatically start within the chip, overwriting memory data at the specified address with the input data.

After the instruction is entered, \overline{CS} can be driven high even while overwrite operation is still in progress internally.

• All Erase

Entering the Erase All instruction causes erase operation to automatically start within the chip, erasing memory data at all addresses.

After the instruction is entered, \overline{CS} can be driven high even while erase operation is still in progress internally.

This command clears the memory data to 0.

• Busy Monitor

Entering the Monitor Busy instruction causes a ready/busy status signal to be output from the DO pin. This output signal is low while the chip is being programmed or collectively erased, and is high after programming or collective erase operation is completed.

The ready/busy status signal is output continuously until $\overline{\text{CS}}$ is driven high.

• Overwrite Enable/Disable

Entering the Enable Overwrite instruction places the chip in overwrite enabled mode, where the Program and Erase All instructions can be entered.

Entering the Disable Overwrite instruction places the chip in overwrite disabled mode, where the Program and Erase All instructions cannot be entered.

Once the chip is placed in overwrite disabled mode, it remains disabled against overwriting until the Enable Overwrite instruction is entered.

Read Auto-incremented

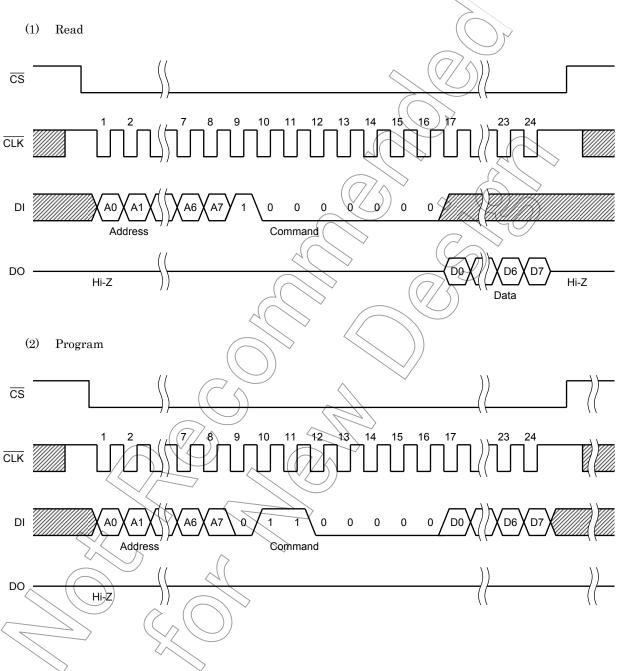
After the data at the specified address is output, the subsequent $\overline{\text{CLK}}$ pulse causes the address to be incremented so that the data at the next address is output automatically. After the data at the last address is output, that at the first address will be read and output.

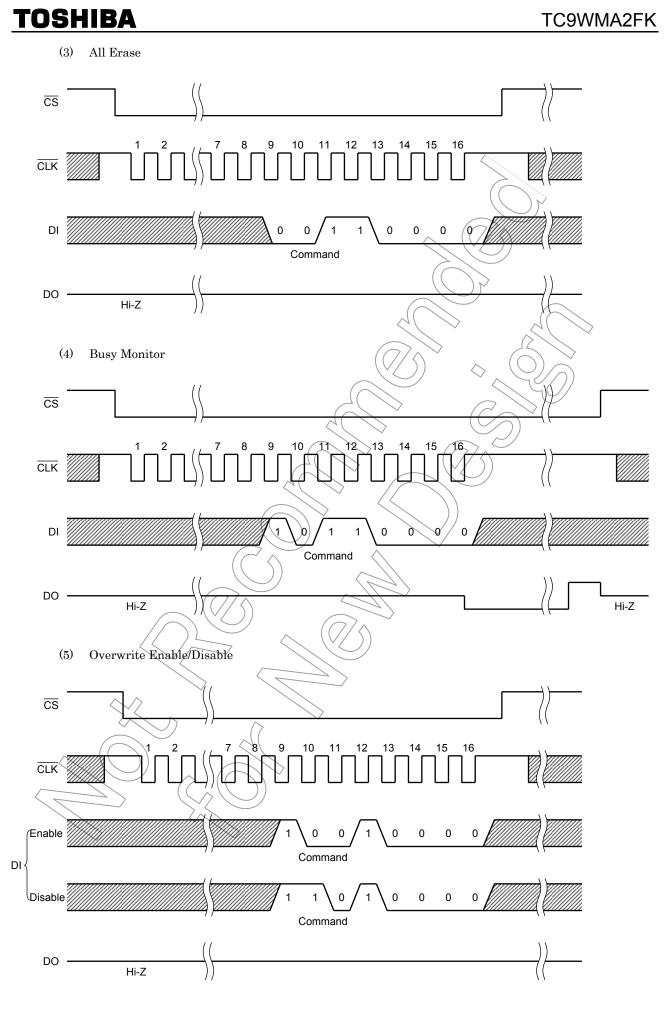
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3. Precautions on Powering Up or Down the Chip

- (1) A wait time of 1 ms is required before the chip can start operation after it is powered up.
- (2) Ensure that $\overline{\text{RST}}$ is low when powering up or down the chip.
- (3) Resetting the chip places it in overwrite disabled mode.

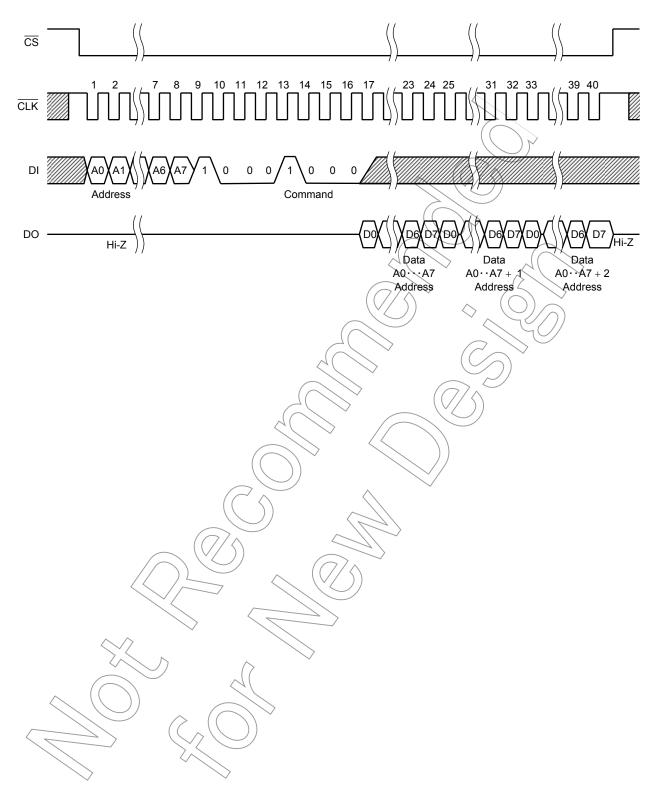
4. Timing Chart







(6) Read Auto-incremented



Absolute Maximum Ratings (Note) (GND = 0 V)

Characteristics	Symbol	Rating	Unit
Power supply voltage	V _{CC}	-0.3~7.0	V
Input voltage	V _{IN}	$-0.3 \sim V_{CC} + 0.3$	V
Output voltage	V _{OUT}	$-0.3 \sim V_{CC} + 0.3$	V
Power dissipation	PD	200 (25°C)	mW
Soldering temperature (in time)	T _{sld}	260 (10 s)	°C
Storage temperature	T _{stg}	-55~125	°C
Operating temperature	T _{opr}	-40~85	°C

Note: Exceeding any of the absolute maximum ratings, even briefly, lead to deterioration in IC performance or even destruction.

Using continuously under heavy loads (e.g. the application of high temperature/current/voltage and the significant change in temperature, etc.) may cause this product to decrease in the reliability significantly even if the operating conditions (i.e. operating temperature/current/voltage, etc.) are within the absolute maximum ratings and the operating ranges.

Please design the appropriate reliability upon reviewing the Toshiba Semiconductor Reliability Handbook ("Handling Precautions"/"Derating Concept and Methods") and individual reliability data (i.e. reliability test report and estimated failure rate, etc).

Operating Ranges (Note 1) (GND = 0 V, $T_{opr} = 40$ to 85°C)

Supply voltage (for reading)	1.8 5.5	V
Supply voltage (for writing) V _C ¢	2.3 5.5	V

Operating Ranges (Note 1) (Vcc = 1.8 to 2.7 V, GND = 0 V, T_{opr} = -40 to 85°C)

Characteristics	Sýmbol	$1.8 \text{ V} \leq \text{V}_{\text{CC}} < 2.3 \text{ V}$		2.3 V ≦ V(Unit	
Characteristics	Syllibol	Min	Max	Min	Max	Offic
Low level input voltage	VIL <	(//	0,15 × V _{CC}	0	0.35	V
High level input voltage	V _{IH1} (Note 1)	0.7 × Vcc	Vcc	1.6	V _{CC}	V
	V _{IH2} (Note 2)	0.8 × V _{CC}	V _{CC}	1.8	V _{CC}	V
Operating frequency	fç⊾k	~	0.25	0	0.5	MHz

Operating Ranges (Note 1) ($V_{CC} = 2.7$ to 5.5 V, GND = 0 V, $T_{opr} = -40$ to 85°C)

Characteristics	Symbol	2.7 V ≦ V _C	C ≦ 3.6 V	4.5 V ≦ V ₀	_{CC} ≦ 5.5 V	Unit
Cridiacienstics	Symbol	Min	Max	Min	Max	Unit
Low level input voltage	\searrow V _{IL}	0	0.45	0	0.7	V
High level input voltage	V _{IH1} (Note 2)	1.6	V _{CC}	2.0	V _{CC}	V
nigh level input voltage	V _{IH2} (Note 3)	2.2	V _{CC}	3.0	V _{CC}	v
Operating frequency	fclk	0	1	0	1	MHz

Note 1: The operating ranges must be maintained to ensure the normal operation of the device. Unused inputs must be tied to either VCC or GND.

Note 2: \overline{CS} , DI, \overline{RST}

Note 3: CLK

Electrical Characteristics

D.C. Characteristics (V_{CC} = 1.8 to 2.7 V, GND = 0 V, T_{opr} = -40 to 85°C)

Characteristics	Symbol	Test Condition	1.8 V ≦ V(_{CC} < 2.3 V	2.3 V ≦ V(Unit	
Characteristics	Symbol	Test Condition	Min	Max	Min	Max	Unit
Input current	ILI		—	±1 <		±1	μA
Output leakage current	I _{LO}		_	±1	\sim	±1	μA
		I _{OH} = -1 mA	—	_	()	_	
High level output voltage	V _{OH}	I _{OH} = –500 μA	—	$+ \bigcirc$	V _{CC} - 0.4	_	V
		I _{OH} = −100 μA	V _{CC} - 0.2	\mathbb{X}))-	_	
		$I_{OL} = 2 \text{ mA}$	—			_	
Low level output voltage	V _{OL}	I _{OL} = 500 μA	—	()	0.4	_	V
		I _{OL} = 100 μA	0.2		- (
Quiescent supply current	I _{CC1} (Note 1)			5	N/2	5	μA
Supply current during read	I _{CC2} (Note 2)			0.5 🚫		1.0	mA
Supply current during all erase/program	I _{CC3} (Note 3)		\rightarrow	- (Z	1.0	mA

D.C. Characteristics (V_{CC} = 2.7 to 5.5 V, GND = 0 V, $T_{opr} = -40$ to 85°C)

Characteristics	Symbol	Test Condition	2.7 V≦V(20 < 3.6 V	4.5 V ≦ V(Unit	
Characteristics	Symbol	Test condition	Min	Max	Min	Max	Unit
Input current	ILI			<u></u> 1	_	±1	μA
Output leakage current	ILO			✓ ±1		±1	μA
		IOH = -1 mA	V _C C – 0.4	_	$V_{CC}-0.4$		
High level output voltage	Voн	ΙοΗ = -500 μΑ	$\widehat{\mathbb{N}}$	_			V
	(//)	I _{OH} = -100 μA		—	—		
		$I_{OL} = 2 \text{ mA}$	0.4	—	0.4	_	
Low level output voltage	VOL	I _{OL} = 500 μA		—	—		V
		JOL = 100 μA		_	_		
Quiescent supply current	V _{ICC1} (Note 1)			5	_	5	μΑ
Supply current during read	I _{CC2} (Note 2)	\langle		1.5	_	2.5	mA
Supply current during all erase/program	I _{CC3} (Note-3)		_	1.0	—	2.0	mA

Note 1: $\overline{CS} = 1$ (except when busy, however)

Note 2: Current that flows for a period between a fall of the 14th CLK pulse and a rise of the 16th CLK pulse when executing the Read instruction.

Note 3: Current that flows while executing the Erase All or Program instruction.

A.C. Characteristics (V_{CC} = 1.8 to 2.7 V, GND = 0 V, T_{opr} = -40 to 85°C)

Characteristics	Currente e l	Test Condition	1.8 V ≦ V(_{CC} < 2.3 V	2.3 V ≦ V ₀	1.1	
Characteristics	Symbol	Test Condition	Min	Max	Min	Max	Unit
Maximum clock frequency	f _{MAX}		0	0.25	0	0.5	MHz
Minimum clock pulse width	twCLK (L)		1.0	-	1.0		
winimum clock pulse width	twCLK (H)		1.0		1.0		μS
Minimum reset pulse width	twrst		1	_			μS
Minimum chip select pulse width	twcs		1	-(7)		_	μS
Reset setup time	t _{RSS}	$\frac{\overline{RST}}{CS}$ setup time when \overline{CS} is switched over	1	XX	2) 1	_	μS
Clock setup time	^t скs	CLK <u>se</u> tup time when CS is switched over	500	\bigcirc	500		ns
CS setup time	tcss	$\overline{\underline{CS}}_{CLK}$ setup time when CLK is switched over	500		500		ns
Propagation delay time	^t pLH t _{pHL} t _{pZH} t _{pZL}	Time from CLK switchover until valid data is output		2.0	P	1.0	μS
(Note)	t _{pLZ} t _{pHZ}	Time from CS switchover until output data goes Hi-Z	> –	2.0	\mathcal{D}	1.0	
Input data setup time	t _s	Input d <u>ata s</u> etup time when CLK is switched over	500		500		ns
Input data hold time	t _h	Input d <u>ata ho</u> ld time when CLK is switched over	500		500		ns

Note: $C_L = 100 \text{ pF}, R_L = 1 \text{ } k\Omega$

A.C. Characteristics (V_{CC} = 2.7 to 5.5 V, GND = 0 V, T_{opr} = -40 to 85°C)

Characteristics	Sumbol	Test Condition	2.7 V ≦ V(_{CC} ≦ 3.6 V	4.5 V ≦ V(_{CC} ≦ 5.5 V	Linit
Characteristics	Symbol	Test Condition	Min	Max	Min	Max	Unit
Maximum clock frequency	f _{MAX}		0	1	0	1	MHz
Minimum clock pulse width	twCLK (L)		0.4	1	0.4		
winimum clock pulse width	twCLK (H)		0.4		0.4		μS
Minimum reset pulse width	twrst		1	_		_	μS
Minimum chip select pulse width	twcs		1				μS
Reset setup time	t _{RSS}	$\frac{\overline{RST}}{CS}$ setup time when \overline{CS} is switched over	1		2) 1	_	μs
Clock setup time	^t скs	CLK <u>se</u> tup time when CS is switched over	250	\bigcirc	250	_	ns
CS setup time	tcss	$\overline{\underline{CS}}$ setup time when CLK is switched over	250	\geq	250		ns
Propagation delay time (Note)	^t pLH t _{pHL} t _{pZH} t _{pZL}	Time from CLK switchover until valid data is output	\square	0.25	R	0.25	μs
	t _{pLZ} t _{pHZ}	Time from CS switchover until output data goes Hi-Z	\rightarrow –	0.5	\mathcal{T}	0.5	
Input data setup time	ts	Input d <u>ata s</u> etup time when CLK is switched over	250		250		ns
Input data hold time	t _h	Input d <u>ata h</u> old time when CLK is switched over	250		250	_	ns

Note: $C_L = 100 \text{ pF}, R_L = 1 \text{ } k\Omega$

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E^2PROM Characteristics (GND = 0 V, 2.3 V \leq V_{CC} \leq 2.7 V, T_{opr} = -40 to 85°C)

Symbol	Test Condition	Min	Тур.	Max	Unit
t _E		_		12	ms
tP		_		12	ms
NEW		1×10 ⁵	_	_	Times
t _{RET}		10			Year
	t _E tP NEW	t _E t _P N _{EW}	t _E — t _P — N _{EW} 1×10 ⁵	$\begin{array}{c c} t_{E} & - & \\ \hline t_{P} & - & \\ \hline N_{EW} & & & \\ \hline \end{array}$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

E^2 PROM Characteristics (GND = 0 V, 3.0 V \leq V_{CC} \leq 5.5 V, T_{opr} = -40 to 85°C)

Characteristics	Symbol	Test Condition	Min	Тур.	Max	Unit
All erase time	tE)^		10	ms
Program time	tP		_	\bigcirc	10	ms
Endurance	NEW		1×10^5	A	\rightarrow	Times
Data retention time	t _{RET}	$(\overline{\alpha})$	10	5	> -	Year
			\sim \sim			

Capacitance Characteristics (Ta = 25°C)

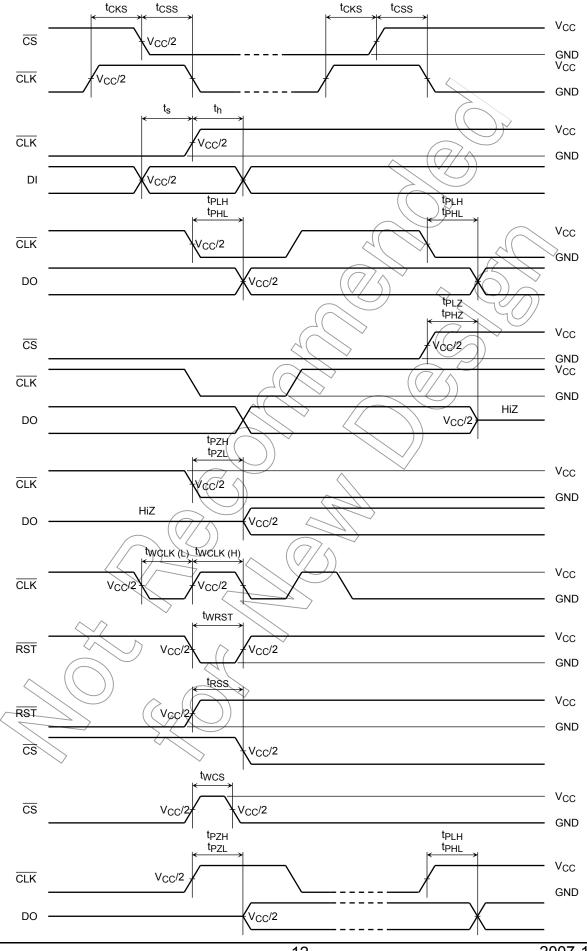
Characteristics	Symbol	Test Condition	$\langle \rangle$	V _{CC} (V)	Тур.	Unit
Input capacitance	C _{IN}		(7/s)	3.3	4	pF
Output capacitance	CO		\mathbf{V}	3.3	3	pF
Equivalent Internal capacitance	C _{PD}	f _{IN} = 1.MHz	(Note)	3.3	8.5	pF

Note: CPD denotes the IC's internal equivalent capacitance calculated from the amount of current it consumes while operating.

The average current consumption during non-loaded operation is obtained from the equations below.

 $I_{CC (Read)} = f_{CLK} \cdot C_{PD} \cdot V_{CC} + I_{CC1} + I_{CC2} \cdot 3/24$ $I_{CC (Prog)} = f_{CLK} \cdot C_{PD} \cdot V_{CC} + I_{CC1} + I_{CC3}$

A.C. Characteristics Timing Chart

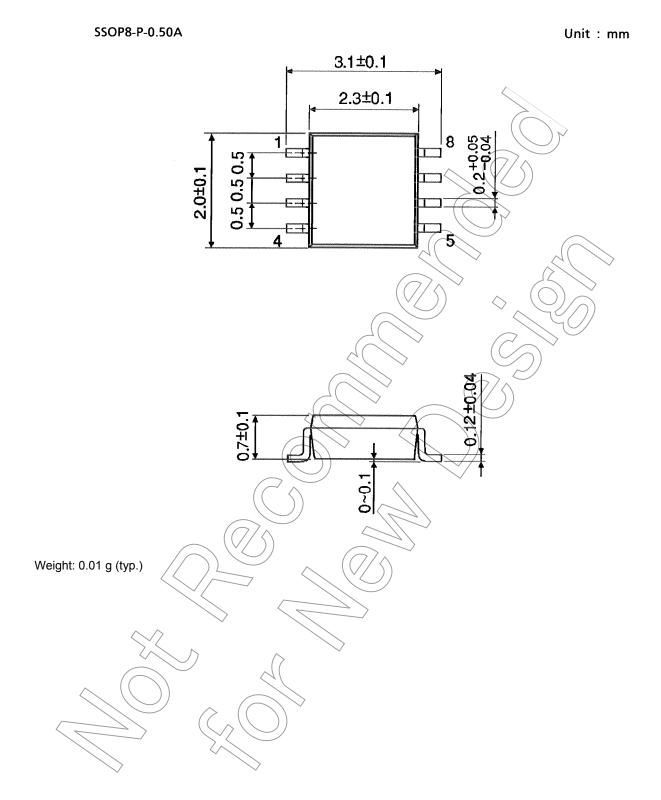


Input/Output Circuits of Pins

Pin Name	Туре	Input/Output Circuit	Remarks			
CS DI RST	Input					
CLK	Input		Hysteresis input			
DO	Output	Output control signal V _{CC}	Initial "HiZ"			

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Package Dimensions



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